Tensor numerical methods in 3D electronic structure calculations

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Overview

Outline of the talk

- 1) Tensor-structured methods in \mathbb{R}^d
 - Basic rank-structured formats
 - Tensor product operations
 - Why Tucker was important
 - Canonical to Tucker tensor approximation
- Start of tensor-structured numerical methods
 - The Hartree-Fock (HF) equation
 - 3D grid-based Hartree and exchamge potentials in 1D complexity
- 3 HF Solver by a standard but 3D grid-based scheme
 - 3D grid-based factorized TEI
 - Core Hamiltonian
 - "Ab-initio" black-box HF solver
 - Grid-based extended and periodic systems
 - Assembled tensor method for lattice sums of long-range potentials

Rank-structured representation of higher order tensors

 $\begin{aligned} &A = [a_{i_1 \dots i_d}] \in \mathbb{R}^{n_1 \times \dots \times n_d}, \quad \ell = 1, \dots, d, \\ &\text{for } n_\ell = n, \quad N = n^d - ``curse \text{ of dimensionality''}. \end{aligned}$

 $\Rightarrow \text{ We need structured representation of tensors:} \\ \hline \text{Tensor product of vectors } u^{(\ell)} = \{u_{i_\ell}^{(\ell)}\}_{i_\ell=1}^n \in \mathbb{R}^{I_\ell} \text{ forms the canonical rank-1 tensor} \\ A_{(1)} = u^{(1)} \otimes \ldots \otimes u^{(d)} \equiv [u_i]_{i \in \mathcal{I}}, \\ \text{with entries } u_i = u_{i_1}^{(1)} \cdots u_{i_d}^{(d)}. \text{ Storage: } dn << n^d. \\ \end{cases}$

Definition 3. The canonical format, $C_{R,n}$

$$A_{(R)} = \sum_{k=1}^{R} c_k u_k^{(1)} \otimes \ldots \otimes u_k^{(d)}, \quad c_k \in \mathbb{R},$$

with normalised $u_k^{(\ell)} \in \mathbb{R}^n$ and the canonical rank $\leq R$.



(1)

Tucker tensor format

Definition. Given the rank parameter $\mathbf{r} = (r_1, \dots, r_d)$, define the Tucker tensor format [Tucker '66].

$$A_{(\mathbf{r})} = \sum_{\nu_1=1}^{r_1} \dots \sum_{\nu_d=1}^{r_d} \beta_{\nu_1 \dots \nu_d} \, \mathbf{v}_{\nu_1}^{(1)} \otimes \dots \otimes \mathbf{v}_{\nu_d}^{(d)}, \tag{2}$$

with orthonormal $v_{\nu_{\ell}}^{(\ell)} \in \mathbb{V}_{\ell} = \mathbb{R}^{I_{\ell}}$ $(1 \le \nu_{\ell} \le r_{\ell})$, and the core tensor

$$\boldsymbol{\beta} = [\beta_{\nu_1, \dots, \nu_d}] \in \mathbb{B}_{\mathbf{r}} = \mathbb{R}^{r_1 \times \dots \times r_d}$$

Using side matrices $V^{(\ell)} = [v_1^{(\ell)} \dots v_{\ell_\ell}^{(\ell)}] \in \mathbb{R}^{n_\ell \times r_\ell}$ and tensor-by-matrix contracted product, $A_{(\mathbf{r})} = \beta \times_1 V^{(1)} \times_2 V^{(2)} \times_3 \dots \times_d V^{(d)}.$



Mixed Tucker-canonical (TC) tensor format



Advantages of the Tucker tensor decomposition:

- 1. Robust algorithm for approximating full format tensors of size n^d .
- 2. Rank reduction of the rank-R canonical tensors with large R.
- 3. Efficient for 3D tensors since r^3 is small.

Multilinear operations in canonical tensor format

$$A_1 = \sum_{k=1}^{R_1} c_k u_k^{(1)} \otimes \ldots \otimes u_k^{(d)}, \quad A_2 = \sum_{m=1}^{R_2} b_m v_m^{(1)} \otimes \ldots \otimes v_m^{(d)}.$$

Euclidean scalar product (complexity $O(dR_1R_2n) \ll n^d$),

$$\langle A_1, A_2 \rangle := \sum_{k=1}^{R_1} \sum_{m=1}^{R_2} c_k b_m \prod_{\ell=1}^d \left\langle u_k^{(\ell)}, v_m^{(\ell)} \right\rangle.$$

Hadamard product of A_1 , A_2

$$A_1 \odot A_2 := \sum_{k=1}^{R_1} \sum_{m=1}^{R_2} c_k b_m \left(u_k^{(1)} \odot v_m^{(1)} \right) \otimes \ldots \otimes \left(u_k^{(d)} \odot v_m^{(d)} \right).$$

Convolution, for d = 3 (complexity $O(R_1R_2n\log n) \ll n^3\log n$ (3D FFT))

$$A_1 * A_2 = \sum_{k=1}^{R_1} \sum_{m=1}^{R_2} c_k b_m (u_m^{(1)} * v_k^{(1)}) \otimes (u_m^{(2)} * v_k^{(2)}) \otimes (u_m^{(3)} * v_k^{(3)})$$

The *unfolding of a tensor* along mode ℓ is a matrix

$$A_{(\ell)} = [a_{ij}] \in \mathbb{R}^{n_{\ell} \times (n_{\ell+1} \cdots n_d n_1 \cdots n_{\ell-1})}$$

whose columns are the respective fibers along ℓ -mode.



Given a tensor $A \in \mathbb{R}^{l_1 \times \dots l_d}$ and a matrix $M \in \mathbb{R}^{J_\ell \times l_\ell}$, we define the mode- ℓ tensor-matrix product by

$$B = A \times_{\ell} M \in \mathbb{R}^{I_1 \times \ldots \times I_{\ell-1} \times J_{\ell} \times I_{\ell+1} \ldots \times I_d},$$

where $b_{i_1,...,i_{\ell-1},j_{\ell},i_{\ell-1},...,i_d} = \sum_{i_{\ell}=1}^{n_{\ell}} a_{i_1,...,i_{\ell-1},i_{\ell},i_{\ell-1},...,i_d} m_{i_{\ell},j_{\ell}}, \quad j_{\ell} \in J_{\ell}.$



Tucker tensor approximation

Multilinear algebra for the problems of chemometrics, psychometrics, data processing, etc. [Tucker '66, De Lathauwer et al, 2000]

$$A_0 \in \mathbb{V}_{\mathbf{n}}$$
: $f(A) := \|A_{(r)} - A_0\|^2 \to \min$ over $A \in \mathcal{T}_{\mathbf{r}}$. (3)

The minimisation problem is equivalent to the maximisation problem

$$g(V^{(1)},...,V^{(d)}) := \left\| A_0 \times_1 V^{(1)^T} \times ... \times_d V^{(d)^T} \right\|^2 \to max$$
(4)

over the set of $V^{(\ell)} \in \mathbb{R}^{n_\ell \times r_\ell}$. For given $V^{(\ell)}$, the core β in minimizer of (3), $A_{(r)} = \beta \times_1 V^{(1)} \times_2 \ldots \times_d V^{(d)}$ is

$$\boldsymbol{\beta} = \boldsymbol{A}_0 \times_1 \boldsymbol{V}^{(1)^T} \times \ldots \times_d \boldsymbol{V}^{(d)^T} \in \mathbb{R}^{r_1 \times \ldots \times r_d}.$$

Complexity for d = 3, $O(n^4 + n^3r + n^2r^2 + nr^3)$, $r = \max_{\ell} r_{\ell}$.

For function related tensors, [B. Khoromskij 2006]:

$$\|A_{(r)}-A_0\| \leq Ce^{-\alpha r}, \text{ with } r=\min_{\ell} r_{\ell}.$$

Full-size tensor to Tucker

Algorithm ALS Tucker $(\mathbb{V}_n \to \mathcal{T}_{r,n})$. Given the input tensor $A \in \mathbb{V}_n$.

Compute an initial guess V₀^(ℓ) (ℓ = 1, ..., d) for the ℓ-mode side-matrices by truncated SVD applied to matrix unfolding A_(ℓ) (cost O(n^{d+1})).

3 For $k = 1 : k_{max}$ do: for each q = 1, ..., d, and with fixed side-matrices $V^{(\ell)} \in \mathbb{R}^{n \times r_{\ell}}$, $\ell \neq q$, optimise the side matrix $V^{(q)}$ via computing the dominating r_q -dimensional subspace (truncated SVD) for the respective matrix unfolding $B_{(q)} \in \mathbb{R}^{n \times \bar{r}_q}$, $\bar{r}_q = r_1...r_{q-1}r_{q+1}...r_d$, corresponding to the *q*-mode contracted product

$$B_{(q)} = A \times_1 V^{(1)T} \times ... \times_{q-1} V^{(q-1)T} \times_{q+1} V^{(q+1)T} ... \times_d V^{(d)T}.$$

Each iteration costs $O(dr^{d-1}n\min\{r^{d-1},n\})$, since $\bar{r}_q = O(r^{d-1})$.

Compute the core β as the representation coefficients of the orthogonal projection of A onto T_n = ⊗^d_{ℓ=1} T_ℓ with T_ℓ = span{v^ℓ_ℓ)^{T_ℓ}/_{ν=1},

$$\boldsymbol{\beta} = \boldsymbol{A} \times_1 \boldsymbol{V^{(1)}}^T \times \ldots \times_d \boldsymbol{V^{(d)}}^T \in \mathbb{B}_{\mathbf{r}},$$

at the cost $O(r^d n)$.

Functional Tucker approximation [B.N. Khoromskij, VKH '06 (CEJM '07)]

$$\begin{split} &f(x), \ x = (x^{(1)}, x^{(2)}, x^{(3)})^T \in \mathbb{R}^3 \text{ is discretized in } [a, b]^3. \text{ Sampling points: } x^{\ell}_{i_\ell} = a_\ell + (i_\ell - \frac{1}{2})(\frac{b-a}{n_\ell}), \ i_\ell = 1, 2, \dots n_\ell. \\ \Rightarrow \text{ We generate a tensor } A \in \mathbb{R}^{n_1 \times n_2 \times n_3} \text{ with entries } a_{ijk} = f(x^{(1)}_i, x^{(2)}_j, x^{(3)}_k). \end{split}$$



 $\text{Example: Slater function } f(x) = \exp(-\alpha \|x\|), \quad E_{FN} = \frac{\|A_0 - A_{(r)}\|}{||A_0||}, \quad E_{FE} = \frac{\|A_0\| - \|A_{(r)}\|}{||A_0||}, \quad E_C := \frac{\max_{i \in \mathcal{I}} |a_{0,i} - a_{r,i}|}{\max_{i \in \mathcal{I}} |a_{0,i}|}.$



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Multigrid Tucker for 3D periodic structures

[VKH '10 (TU Berlin, dissertation)]



The "multi-centered Slater potential" obtained by displacing a single Slater potential with respect to the $m \times m \times m$ spatial grid of size H > 0, (here m = 10)

$$g(x) = \sum_{i=1}^{m} \sum_{j=1}^{m} \sum_{k=1}^{m} e^{-\alpha \sqrt{(x_1 - iH)^2 + (x_2 - jH)^2 + (x_3 - kH)^2}}.$$

Canonical to Tucker Approximation

[B.N. Khoromskij, VKH '08 (SISC '09)] Theorem.

Let $A \in \mathcal{C}_{R,n}$. Then the minimisation problem

$$A \in \mathcal{C}_{R,\mathbf{n}} \subset \mathbb{V}_{\mathbf{n}} : \quad A_{(\mathbf{r})} = \operatorname{argmin}_{V \in \mathcal{T}_{\mathbf{r},\mathbf{n}}} \|A - V\|_{\mathbb{V}_{\mathbf{r}}}, \tag{5}$$

$$[Z^{(1)},...,Z^{(d)}] = \operatorname{argmax}_{V^{(\ell)} \in \mathcal{M}_{\ell}} \left\| \sum_{\nu=1}^{R} c_{\nu} \left(V^{(1)}{}^{T} u_{\nu}^{(1)} \right) \otimes ... \otimes \left(V^{(d)}{}^{T} u_{\nu}^{(d)} \right) \right\|_{\mathbb{V}_{r}}^{2},$$

Init. guess: RHOSVD $Z_0^{(\ell)} \Rightarrow$ the truncated SVD of $U^{(\ell)} = [u_1^{(\ell)}...u_R^{(\ell)}]$, under the compatibility condition

$$r_{\ell} \leq rank(U^{(\ell)})$$
 with $U^{(\ell)} = [u_1^{(\ell)}...u_R^{(\ell)}] \in \mathbb{R}^{n imes R}$

Error bounds for RHOSVD

$$\|A - A^0_{(\mathbf{r})}\| \le \|\mathbf{c}\| \sum_{\ell=1}^d (\sum_{k=r_\ell+1}^{\min(n,R)} \sigma^2_{\ell,k})^{1/2}, \quad ext{where } \|\mathbf{c}\|^2 = \sum_{\nu=1}^R c^2_{\nu}.$$

C2T + T2C rank reduction



 $R_t \ll R$, $R_t < r^2$







Tensor formats for higher dimensions

Matrix product states tensor factorization (MPS): [White 1992], [Cirac, Verstraete 2004] [Vidal 2003] (reinvented as tensor train format by [Oseledets, Tyrtyshnikov 2009])

$$a_{i_1,i_2,i_3,i_4,i_5} = \prod_{k=1}^5 B_k(i_k), \quad A \in \mathbb{R}^{n_1 \times n_2 \times n_3 \times n_4 \times n_5}, \quad B_k \in \mathbb{R}^{r_{k-1} \times r_k}, \quad r_0 = r_5 = 1.$$



Quantized tensor format (for function related vectors/tensors):[Khoromskij 2009, (CA '11)]

$$2^{L} >> 2Lr^{2}, \qquad r = 1 \text{ for } e^{-\alpha ||x||}, \quad r = 2 \text{ for } sin(x), \text{ etc}$$

$$P = 2 \text{ for } sin(x), \text{ etc}$$

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Grid-based approaches and related tensor formats

- Sparse grids: M. Griebel, H. Yserentant, C.Schwab, et al. 1990.
- Wavelets with canonical format: G. Beylkin, M. Mohlenkamp (2002), R. Schneider, H.-J. Flad, W. Hackbusch, B. Khoromskij (2005).
- Functional Tucker, canonical-to-Tucker transform (2006-2008) tensor-structured numerical methods, 3D convolution integrals (2008)
 V. Khoromskaia, B. Khoromskij.
- 3D grid based solvers for the Hartree-Fock equation (2009-2012), 3D grid-based TEI (2011-12):
 V. Khoromskaia, B. Khoromskij, H.-J. Flad, R. Schneider.
- Matrix Product States, Tensor Train (TT): S. White (1992), Cirac, Verstraete (2004), I. Oseledets, E. Tyrtyshnikov (2009).
- Quantized vector/tensor low rank approximation: B. Khoromskij (2009).
- QTT library:
 - I. Oseledets, B. Khoromskij, S. Dolgov, et. al. (2009-2012).
- Hierarchical Tucker, hierarchical SVD of tensors:
 W. Hackbusch, L. Grasedyck (2009). D. Kressner, C. Tobler, (2010)
- Best TT approximation:
 R. Schneider, T. Rohwedder, S. Holtz (2010-2012).

The Hartree-Fock equation, standard Galerkin scheme

Nonlinear eigenvalue problem

$$\mathcal{F}\varphi_i(x) \equiv (-\frac{1}{2}\Delta + V_c + V_H - \mathcal{K})\varphi_i(x) = \lambda_i \varphi_i(x), \quad i = 1, ..., N_{orb}.$$

The Fock operator \mathcal{F} depends on $\tau(x, y) = 2 \sum_{i=1}^{N_{orb}} \varphi_i(x) \varphi_i(y)$,

$$\mathcal{F}\varphi := \left[-\frac{1}{2}\Delta - \sum_{\nu=1}^{M} \frac{Z_{\nu}}{\|x - a_{\nu}\|} + \int_{\mathbb{R}^{3}} \frac{\tau(y, y)}{\|x - y\|} dy\right]\varphi - \frac{1}{2} \int_{\mathbb{R}^{3}} \frac{\tau(x, y)}{\|x - y\|} \varphi(y) dy.$$

Numerical challenges: high accuracy, 3D and 6D singular integrals, strong nonlinearity.

Expansion of molecular orbitals in $\{g_{\mu}\}_{1 \leq \mu \leq N_b}$,

$$arphi_i(\mathbf{x}) = \sum_{\mu=1}^{N_b} c_{i\mu} g_{\mu}(\mathbf{x}), \quad i = 1, ..., N_{orb},$$

yields the Galerkin system of nonlinear equations for coefficients matrix $C = \{c_{i\mu}\} \in \mathbb{R}^{N_{orb} \times N_b}$, (and density matrix $D = 2CC^* \in \mathbb{R}^{N_b \times N_b}$)

$$F(C)C = SC\Lambda, \quad \Lambda = diag(\lambda_1, ..., \lambda_{N_b}), \quad C^TSC = I_{N_b},$$

where F(C) = H + J(C) + K(C).

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Standard Galerkin scheme

Precomputed: core Hamiltonian $H = \{h_{\mu\nu}\}$

$$h_{\mu\nu} = \frac{1}{2} \int_{\mathbb{R}^3} \nabla g_{\mu} \cdot \nabla g_{\nu} dx + \int_{\mathbb{R}^3} V_c(x) g_{\mu} g_{\nu} dx \quad 1 \leq \mu, \nu \leq N_b.$$

and two-electron integrals (TEI)

$$b_{\mu\nu\kappa\lambda} = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{g_{\mu}(x)g_{\nu}(x)g_{\kappa}(y)g_{\lambda}(y)}{\|x-y\|} dxdy.$$

Then the EVP

$$F(C)C = SC\Lambda$$

is solved iteratively, using DIIS [Pulay '80] and updating F(C) = H + J(C) + K(C),

$$J(C)_{\mu
u} = \sum_{\kappa,\lambda=1}^{N_b} b_{\mu
u,\kappa\lambda} D_{\kappa\lambda}, \quad K(C) = -rac{1}{2} \sum_{\kappa,\lambda=1}^{N_b} b_{\mu\lambda,
u\kappa} D_{\kappa\lambda}.$$

The ground state energy

$$E_{HF} = 2\sum_{i=1}^{N_{orb}} \lambda_i - \sum_{i=1}^{N_{orb}} \left(\widetilde{J}_i - \widetilde{K}_i \right),$$

where $\widetilde{J}_i = (\varphi_i, V_H \varphi_i)$ and $\widetilde{K}_i = (\varphi_i, K \varphi_i)$.

Competing grid-based tensor approach to computational quantum chemistry

Benchmark packages (analytic): MOLPRO [Werner et al.], GAUSSIAN, CRYSTAL, ... Grid-based tensor methods in HF calculations: [Khoromskii, VKH, Flad, 2009, SISC '11],

- Example of a compact molecule computed by tensor method: Alanin aminoacid
- 3D lattice structure



Grid-based tensor numerical methods look promising for computation of structured extended systems and periodic compounds.

Basic building blocks

[VKH, Khoromskij '08 - '13]

- **Canonical, Tucker and QTT** tensor arithmetics.
- ▶ Grid basis $\{g_{\mu}\}$, and core Hamiltonian in $(O(n) \text{ and } O(\log n) \text{ operations}.$
- **Fast 3D tensor convolution** in $O(n \log n)$ operations.
- ▶ Direct/redundancy free factorizations of TEI matrix $B = [b_{\mu\nu;\kappa\lambda}] \in \mathbb{R}^{N_b^2 \times N_b^2}$.

Cholesky decomposition (ε-approximation) of *B*: Compute columns and diagonal of *B* using precomputed factorization,

$$B = mat(\mathbf{B}) := [b_{\mu
u,\kappa\lambda}] pprox LL^T, \quad R_B = rank_{arepsilon}(B) = O(N_b).$$

QTT compression of the Cholesky factor $L \in \mathbb{R}^{N_b^2 \times R_B}$: $N_b^2 \Rightarrow N_{orb}^2$, $N_b \approx 10N_{orb}$.

- **DIIS** self-consistent iteration (standard in quantum chemistry).
- MP2 energy correction via tensor factorizations.

Discretization of 3D basis functions



The computational box: $[-b, b]^3$, $b \approx 15 \stackrel{\circ}{A}$ $n \times n \times n$ 3D Cartesian grid, $n \sim 10^5$

$$g_k(x) = p_k(x_1, x_2, x_3)e^{\alpha_k(x_1^2 + x_2^2 + x_3^2)}$$

the continuous basis functions $g_k(x)$: $I_0 : g_k \to \overline{g}_k := \sum_{i \in \mathcal{I}} g_k(x_i)\zeta_i(x)$.

$$g_{k}(x) \approx \mathbf{I}_{0}g_{k} := \overline{g}_{k}(x) = \prod_{\ell=1}^{3} \overline{g}_{k}^{(\ell)}(x_{\ell}) = \prod_{\ell=1}^{3} \sum_{i_{\ell}=1}^{n} g_{k}^{(\ell)}(x_{\ell,i_{\ell}})\zeta_{i_{\ell}}^{(\ell)}(x_{\ell}), \ \ell = 1, \ 2, \ 3$$

rank-1 tensors: $\mathbf{G}_{k} = G_{k}^{(1)} \otimes G_{k}^{(2)} \otimes G_{k}^{(3)}$, with $G_{k}^{(\ell)} = \{g_{k}^{(\ell)}(x_{\ell,i_{\ell}})\}_{i_{\ell}=1}^{n} \in \mathbb{R}^{I_{\ell}}.$

Example: 3D grid-based Hartree potential in 1D complexity

$$V_{H}(x) := \int_{\mathbb{R}^{3}} \frac{\rho(y)}{\|x - y\|} \, dy \qquad \rho(x) = 2 \sum_{a=1}^{N_{orb}} (\varphi_{a})^{2}, \quad x \in \mathbb{R}^{3}$$
$$\varphi_{a}(x) = \sum_{\mu=1}^{N_{b}} c_{a\mu} g_{\mu}(x), \quad a = 1, ..., N_{orb},$$
$$N_{orb} \left(N_{b} N_{b} \right)$$

$$\begin{split} \rho &\approx \boldsymbol{\Theta} : \quad = \quad \sum_{a=1}^{N_{orb}} \left(\sum_{\kappa=1}^{N_b} \sum_{\lambda=1}^{N_b} c_{\kappa a} c_{\lambda a} \boldsymbol{\mathsf{G}}_{\kappa} \odot \boldsymbol{\mathsf{G}}_{\lambda} \right) \\ &= \quad \sum_{m=1}^{R_\rho} c_m u_m^{(1)} \otimes u_m^{(2)} \otimes u_m^{(3)}, \quad u_m^{(\ell)} = \boldsymbol{\mathsf{G}}_{\kappa}^{(\ell)} \odot \boldsymbol{\mathsf{G}}_{\lambda}^{(\ell)} \in \mathbb{R}^n. \end{split}$$

 $R_{\rho}(CH_4) = 1540, \quad R_{\rho}(C_2H_6) = 4656, \quad R_{\rho}(H_2O) = 861$

Multigrid C2T + T2C tensor rank reduction: $\Theta \Rightarrow \Theta'$

 $rank(\Theta) \approx 10^4 \quad \Rightarrow \quad rank(\Theta') \sim 10^2.$

Start of tensor-structured numerical methods in 1D complexity

Example: 3D grid-based Hartree potential in 1D complexity [Khoromskij, VKH '08 (SISC 2009)]

The Newton kernel $P_N = \left[\langle \frac{1}{\|x\|}, \zeta_i \rangle \right]$, ζ_i p.w.c., by *sinc*-quadratures. Rank $(P_N) \sim 20 \div 30$. [Bertoglio, Khoromskij '08 (CPC 2012)]

The tensor-product convolution [Khoromskij '08], (accuracy $O(h^2)$)

$$\begin{split} V_{H} &= \rho * \frac{1}{\|\cdot\|} \approx \Theta' * P_{N} \\ &= \sum_{m'=1}^{R_{\rho_{r}}} \sum_{k=1}^{R_{N}} c_{m'} b_{k} \left(u_{m'}^{(1)} * v_{k}^{(1)} \right) \otimes \left(u_{m'}^{(2)} * v_{k}^{(2)} \right) \otimes \left(u_{m'}^{(3)} * v_{k}^{(3)} \right). \end{split}$$

The Coulomb matrix

$$\begin{split} J(C)_{\mu\nu} &= \int_{R^3} g_{\mu}(x) V_{H}(x) g_{\nu}(x) dx \approx \int_{\mathbb{R}^3} \overline{g}_{\mu}(x) V_{H}(x) \overline{g}_{\nu}(x) \\ &\approx \langle G_{\mu} \odot G_{\nu}, \Theta' * P_N \rangle, \quad 1 \leq \mu, \nu \leq N_b. \end{split}$$

 $W_{C*C} = O(R_{\rho_r} R_N n \log n)$

Tensor-product convolution vs. 3D FFT

[Khoromskij, VKH '08 (SISC 2009)]

The cost of computation of V_H by tensor product convolution (1D FFT):

 $\mathcal{N}_{C*C} = O(R_{\rho_r} R_N n \log n)$

instead of $O(n^3 \log n)$ for 3D FFT.

n ³	128 ³	256 ³	512 ³	1024 ³	2048 ³	4096 ³	8192 ³	16384 ³
FFT ₃	4.3	55.4	582.8	~ 6000	-	-	-	~ 2 years
<i>C</i> * <i>C</i>	0.2	0.9	1.5	8.8	20.0	61.0	157.5	299.2
C2T	4.2	4.7	5.6	6.9	10.9	20.0	37.9	86.0

CPU time (in sec) for the computation of V_H for H_2O .

(3D FFT time for $n \ge 1024$ is obtained by extrapolation).

Start of tensor-structured numerical methods in 1D complexity

Example 2: TS computation of the exchange matrix

[VKH, 2010]

$$K_{k,m} := \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} g_k(x) \frac{\varphi_a(x)\varphi_a(y)}{|x-y|} g_m(y) dx dy, \quad k, m = 1, \dots N_b$$

1. Convolution

$$W_{a,m}(x) = \int_{\mathbb{R}^3} \frac{\varphi_a(y)g_m(y)}{|x-y|} dy \approx \overline{W}_{a,m} := \left[G_m \odot \sum_{\nu=1}^{N_b} c_{\nu a} G_{\nu}\right] * P_N,$$

2. Scalar products

$$V_{km,a} = \int_{\mathbb{R}^3} \varphi_a(x) g_k(x) W_{a,m}(x) dx \approx \overline{V}_{km,a} := \langle G_k \odot \left[\sum_{\mu=1}^{N_b} c_{\mu a} G_{\mu} \right], \overline{W}_{am} \rangle.$$

3. The exchange matrix

$$K_{k,m} = \sum_{a=1}^{N_{orb}} \overline{V}_{km,a}.$$

Grid-based two-electron integrals (TEI)

[VKH, Khoromskij, Schneider, '12]

$$\begin{split} b_{\mu\nu\kappa\lambda} &= \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{g_{\mu}(x)g_{\nu}(x)g_{\kappa}(y)g_{\lambda}(y)}{\|x-y\|} dx dy = \langle \mathbf{G}_{\mu} \odot \mathbf{G}_{\nu}, \mathbf{P}_{\mathcal{N}} * (\mathbf{G}_{\kappa} \odot \mathbf{G}_{\lambda}) \rangle_{n^{\otimes 3}}, \\ \mathbf{G}_{\mu} &= G_{\mu}^{(1)} \otimes G_{\mu}^{(2)} \otimes G_{\mu}^{(3)} \in \mathbb{R}^{n \times n \times n}. \\ \mathbf{G}^{(\ell)} &= \left[G_{\mu}^{(\ell)} \odot G_{\nu}^{(\ell)} \right]_{1 \leq \mu, \nu \leq N_b} \in \mathbb{R}^{n \times N_b^2} \quad \ell = 1, 2, 3. \end{split}$$

Factorization ("1D density fitting") by Cholesky decomposition of $G^{(\ell)}G^{(\ell)T}$:

$$G^{(\ell)} \cong U^{(\ell)} V^{(\ell)^{T}}, \quad U^{(\ell)} \in \mathbb{R}^{n \times R_{\ell}}, \quad V^{(\ell)} \in \mathbb{R}^{N_{b}^{2} \times R_{\ell}},$$

⇒ number of convolutions is reduced from N_b^2 to $R_\ell \le N_b$, n = 32768 (up to 131072), $N_b^2 \sim 28000$ (40000 for alanine):

 ε -rank reduction for glycine: from $N_{h}^{2} = 28900$, to $R_{\ell} \sim 100 \div 220$.

Fast convolution via tensor approximation of Green's kernel

Tensor approximation of the Newton kernel using Laplace transform and sinc-quadratures: [Gavrilyuk, Hackbusch, Khoromskij '08] [Bertoglio, Khoromskij '10]

Green's function for Δ in \mathbb{R}^3 , via (2M + 1)-term sinc-quadrature approximation

$$\frac{1}{\|x\|} = \int_0^\infty e^{-t^2 \|x\|^2} dt \approx \sum_{k=-M}^M c_k e^{-t_k^2 \|x\|^2} = \sum_{k=-M}^M c_k \prod_{\ell=1}^3 e^{-t_k^2 x_\ell^2} \quad \mapsto \mathbf{P}_{\mathcal{N}}.$$

 $\mathbf{P}_{\mathcal{N}} \in \mathbb{R}^{n \times n \times n}$, can. rank of $\mathbf{P}_{\mathcal{N}} R_{\mathcal{N}} \leq 30$.

Tensor-product convolution, $O(n \log n)$:

[Khoromskij '08]

[Khoromskij, Khoromskaia '09]

$$U * P_N = \sum_{k=1}^{R_F} \sum_{m=1}^{R_N} c_k b_m (u_m^{(1)} * p_k^{(1)}) \otimes (u_m^{(2)} * p_k^{(2)}) \otimes (u_m^{(3)} * p_k^{(3)})$$

n ³	512 ³	1024 ³	2048 ³	4096 ³	8192 ³	16384 ³	32768 ³
FFT_3	37.5	350.6	~ 3500	-	-	-	~ 1.2 years
$C_{R_F} * C_{R_N}$	2.4	6.7	14.6	44	107	236	535

 $\begin{array}{l} \mbox{CPU time (in sec) for TEI: } \frac{1}{\|x\|} \ast g_{\mu}g_{\nu}, \ \mu, \nu = 1, ..., N_b, \ \varepsilon = 10^{-7}, \\ H_2O, \ N_b = 41, \quad \frac{N_b(N_b+1)}{2} \mapsto R_F = 71, \quad R_{\mathcal{N}} = 27. \end{array}$

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Factorized TEI

The Newton kernel: $P^{(\ell)} \in \mathbb{R}^{n \times R_N}$ are the factor matrices in the rank- R_N canonical tensor $\mathbf{P}_N \in \mathbb{R}^{n \times n \times n}$.

$$B \cong B_{\varepsilon} := \sum_{k=1}^{R_{\mathcal{N}}} \odot_{\ell=1}^{3} V^{(\ell)} M_{k}^{(\ell)} V^{(\ell)^{T}} \in \mathbb{R}^{N_{b}^{2} \times N_{b}^{2}}$$

with the convolution matrix

$$M_{k}^{(\ell)} = U^{(\ell)^{T}}(P_{k}^{(\ell)} *_{n} U^{(\ell)}) \in \mathbb{R}^{R_{\ell} \times R_{\ell}}, \quad k = 1, ..., R_{\mathcal{N}}.$$

The diagonal elements and j-column in the TEI matrix B:

$$B(i,i) = \sum_{k=1}^{R_{\mathcal{N}}} \odot_{\ell=1}^{3} V^{(\ell)}(:,i) M_{k}^{(\ell)} V^{(\ell)}(:,i)^{T}.$$

$$B(:,j) = \sum_{k=1}^{R_{\mathcal{N}}} \odot_{\ell=1}^{3} V^{(\ell)} M_{k}^{(\ell)} V^{(\ell)}(:,j)^{T},$$

Cholesky decomposition (ε -approximation)

$$B := mat(\mathbf{B}) = [b_{\mu
u,\kappa\lambda}] pprox LL^T, \quad L \in \mathbb{R}^{N_b^2 imes R_B},$$

with $R_B \sim N_b$.

Representation complexity of **B** using the quantized tensor format can be reduced to $O(N_b N_{orb}^2)$ (instead of $O(N_b^3)$). $(N_b \sim 10N_{orb})$.

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Laplacian in Gaussian basis

[VKH, Andrae, Khoromskij, CPC'12]

For a function in Gaussian basis $\{g_k(x)\}_{1\leq k\leq N_b}$, $x\in \mathbb{R}^3$, the 3D Laplace operator

$$A_g = \{a_{km}\} \in \mathbb{R}^{N_b imes N_b}$$
 with $a_{km} = \langle \Delta g_k(x), g_m(x) \rangle$.

The discete 3D Laplace operator $\Delta_3 \in \mathbb{R}^{n^3 imes n^3}$

$$\Delta_{3} = \Delta_{1}^{(1)} \otimes I^{(2)} \otimes I^{(3)} + I^{(1)} \otimes \Delta_{1}^{(2)} \otimes I^{(3)} + I^{(1)} \otimes I^{(2)} \otimes \Delta_{1}^{(3)},$$

where $\Delta_1 = \frac{1}{h} tridiag \{-1, 2, -1\}$. Given $\mathbf{G}_k = G_k^{(1)} \otimes G_k^{(2)} \otimes G_k^{(3)}$, $A_g \approx A_G = \{\overline{a}_{km}\}$,

$$\begin{split} \bar{a}_{km} &= \langle \Delta_1 G_k^{(1)}, G_m^{(1)} \rangle \langle G_k^{(2)}, G_m^{(2)} \rangle \langle G_k^{(3)}, G_m^{(3)} \rangle \\ &+ \langle G_k^{(1)}, G_m^{(1)} \rangle \langle \Delta_1 G_k^{(2)}, G_m^{(2)} \rangle \langle G_k^{(3)}, G_m^{(3)} \rangle \\ &+ \langle G_k^{(1)}, G_m^{(1)} \rangle \langle G_k^{(2)}, G_m^{(2)} \rangle \langle \Delta_1 G_k^{(3)}, G_m^{(3)} \rangle \\ &= \langle \Delta_3 \mathbf{G}_k, \mathbf{G}_m \rangle. \end{split}$$

Complexity (O(n)).

Quantized tensor approximation of $O(\log n)$ complexity introduced in [Khoromskij '09,'11] is used for quantized tensor calculation of the Laplacian in [Kazeev, Khoromskij, '12],

scheme Core Hamiltonian

Laplacian in Gaussian basis

[VKH, '13]

р	15	16	17	18	19	20
$n^3 = 2^{3p}$	32767 ³	65535 ³	131071 ³	262143 ³	524287 ³	1048575 ³
$err(A_G)$	0.0027	$6.8 \cdot 10^{-4}$	$1.7 \cdot 10^{-4}$	$4.2 \cdot 10^{-5}$	$1.0\cdot10^{-5}$	$2.6 \cdot 10^{-6}$
RE	-	$1.0 \cdot 10^{-5}$	$8.3 \cdot 10^{-8}$	$2.6 \cdot 10^{-9}$	$3.3 \cdot 10^{-10}$	0
time (sec)	12.8	17.4	25.7	42.6	77	135
Δa_{11}	49	12	3	0.7	0.19	0.0480
RE	-	0.3	0.0014	$3.3 \cdot 10^{-5}$	$3.3 \cdot 10^{-5}$	$3.3 \cdot 10^{-5}$

3D grid-based quantized tensor calculations for the water molecule (H₂O): accuracy and times vs 3D grid size for the Laplace Galerkin matrix $err(A_G)$ (discretized basis of $N_b = 41$ Cartesian Gaussians).

scheme Core Hamiltonian

Tensor-based nuclear potential

[VKH, Andrae, Khoromskij, CPC'12] [VKH, '13]

$$\begin{split} V_{c}(x) &= -\sum_{\alpha=1}^{M} \frac{Z_{\alpha}}{\|x - a_{\alpha}\|}, \quad Z_{\alpha} > 0, \ a_{\alpha} \in \mathbb{R}^{3}, \qquad \mathsf{P}_{c} = \sum_{\alpha=1}^{M} Z_{\alpha} \mathsf{P}_{c,\alpha}, \\ \overline{v}_{km} &= \int_{\mathbb{R}^{3}} V_{c}(x) \overline{g}_{k}(x) \overline{g}_{m}(x) dx \approx \langle \mathsf{G}_{k} \odot \mathsf{G}_{m}, \mathsf{P}_{c} \rangle, \quad 1 \leq k, m \leq N_{b}. \end{split}$$

 V_c for ethanol molecule (C₂H₅OH) at two levels: z = 0 and z = 0.75 au,



Tensor-based Core Hamiltonian

Laplace and nuclear potential calculations for CH₄, ($N_b = 55$). Difference between the 3D grid-based and analytical calculations in Galerkin matrices

$$Er(A_G) = \frac{\|A_g - A_G\|}{\|A_g\|}, \quad Er(V_G) = \frac{\|V_g - V_G\|}{\|V_g\|}.$$

$N^3 = 2^{3p}$	8192 ³	16384 ³	32768 ³	65536 ³	131072 ³
<i>h</i> (in au)	0.0036	0.0018	$8.9 \cdot 10^{-4}$	$4.4 \cdot 10^{-4}$	$2.2 \cdot 10^{-4}$
$Er(A_G)$	0.02	0.052	0.0013	$3.2 \cdot 10^{-4}$	$8 \cdot 10^{-5}$
RE	-	$2.6 \cdot 10^{-4}$	0	$2.0 \cdot 10^{-6}$	$1.7 \cdot 10^{-8}$
$Er(V_G)$	0.012	0.0029	$7.0 \cdot 10^{-4}$	$1.7 \cdot 10^{-4}$	$4.3 \cdot 10^{-5}$
RE	-	$2.6 \cdot 10^{-4}$	$2.0 \cdot 10^{-5}$	$3.0 \cdot 10^{-6}$	$1.2 \cdot 10^{-7}$

Note: $2.2 \cdot 10^{-4}au = 1.164$ Å = 11.64 femtometers (10^{-15} m), which is \sim to size of atomic radii in a molecule. (Atomic radius of Oxygen is 60 pm, Hydrogen 25 pm.)

 $1 fm = 10^{-15}$ m, $1 pm = 10^{-12}$ m, $1 \stackrel{o}{A}= 10^{-10}$ m.

Self-consistent iteration for nonlinear EVP

[VKH, '13, preprint] [VKH, Khoromskij '13] EVP algorithm for black-box solver:

$$F(C)C = SC\Lambda$$
, $F = H_0 + J(C) - K(C)$,

- Initial guess for J = 0, K = 0, $F(0) = H_0$.
- solve EVP $[H_0 + J(C) K(C)]C = SC\Lambda$.
- Update of J(C) and K(C):

 \triangleright Coulomb matrix: given $\overline{D} = vec(D)$,

$$\operatorname{vec}(J) = B\overline{D} \approx L(L^T\overline{D}).$$

 \triangleright HF exchange: using $D = 2CC^T$ and $B = LL^T$,

$$\mathcal{K}(D)_{\mu
u} = -\sum_{i=1}^{N_{orb}}\sum_{k=1}^{R_B} (\sum_{\lambda} L_{\mu\lambda k} C_{\lambda i}) (\sum_{\kappa} C_{\kappa i} L_{\kappa
u k}),$$

 $[L_{\mu\nu k}] = reshape(L, [N_b, N_b, R_B])$ is the $N_b \times N_b \times R_B$ -folding of the Cholesky fact. L.

DIIS for providing convergence.

TEI based nonlinear 3D EVP solver

[VKH, 2013]

DIIS iteration for amino acids glycine (C₂ H₅N O₂) with TEI on $n^3 = 131072^3$ and alanine (C₃H₇N O₂) with TEI on $n^3 = 32768^3$.



H₂O: iteration with core Hamiltonian on 131072³; convergence in energy; last k + 27 iterations.

Grid-based calculations of large extended/periodic systems

[VKH, Khoromskij Preprint MIS MPG'13] Main ingredients in tensor approach:

- Computing large lattice sums of the Newton kernels.
- Lattice-structured TEI computation.
- Block-structured representation of the Fock matrix.
- Fast diagonalisation of the Fock matrix.



Figure: The periodic structure of the size $4.5 \times 4.5 \times 1.5 \stackrel{\circ}{A}^3$ in the box $[-b, b]^3$, with b = 16 au ($\sim 8.5 \stackrel{\circ}{A}$).

Lattice sums of electrostatic potentials by assembled tensor approximation

Fast and accurate calculation of lattice sums of electrostatic potentials (absolute accuracy 10^{-14})



Assembled vectors along x- y- and z-axis, for a cluster of $32 \times 16 \times 8$ Hydrogen atoms in a rectangular box of size $\sim 55.4 \times 33.6 \times 22.4 au^3$ (Dirichle bound. cond.). The resulting sum of 4096 nuclei potentials at cross-section with z = 0.83 au.

Resume

- Development of the tensor-structured numerical methods resulted in a "black box" solver for the Hartree-Fock equation in a general basis.
- Grid-based calculation of 3D integral operators with linear scaling in 1D.
- Grid-based 3D Laplace and nuclear potential operators with controllable accuracy.
- Two-electron integrals in a general basis.
- General bases can include any physically relevant functions (local finite elements, AO, Slater, truncated plane waves, etc).
- Robust tensor rank reduction algorithms (C2T+T2C, ACA+QR, etc.).
- Numerical tests for compact molecules confirm efficiency of algorithms.
- TS numerical methods applicable to post-HF models: MP2.
- Tensor numerical methods have a big potential for periodic and quasi-periodic structures.

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Thank you for attention

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