# Graph Polynomials from Laplacians 

November 11, 2022

## Kirchhoff polynomials

Given a graph $G$, we associate a parameter $a_{j}$. The Kirchhoff polynomial of $G$ is defined by

$$
\mathcal{K}\left(a_{1}, \ldots, a_{n}\right)=\sum_{T \in \mathcal{T}_{1}} \prod_{e_{j} \in T} a_{j} .
$$

## Kirchhoff polynomials

Given a graph $G$, we associate a parameter $a_{j}$. The Kirchhoff polynomial of $G$ is defined by

$$
\mathcal{K}\left(a_{1}, \ldots, a_{n}\right)=\sum_{T \in \mathcal{T}_{1}} \prod_{e_{j} \in T} a_{j} .
$$

In physics parameters $a_{j}$ are only associated to internal edges. We set

$$
\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{i n t}}\right)=\mathcal{K}\left(G_{i n t}\right)=\sum_{T \in \mathcal{T}_{1}} \prod_{e_{j} \in(T \cap E)} a_{j} .
$$

## Kirchhoff polynomials

Given a graph $G$, we associate a parameter $a_{j}$. The Kirchhoff polynomial of $G$ is defined by

$$
\mathcal{K}\left(a_{1}, \ldots, a_{n}\right)=\sum_{T \in \mathcal{T}_{1}} \prod_{e_{j} \in T} a_{j} .
$$

In physics parameters $a_{j}$ are only associated to internal edges. We set

$$
\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{i n t}}\right)=\mathcal{K}\left(G_{i n t}\right)=\sum_{T \in \mathcal{T}_{1}} \prod_{e_{j} \in(T \cap E)} a_{j} .
$$

There is a simple relation between $\mathcal{K}_{\text {int }}$ and $\mathcal{U}$ :

$$
\mathcal{U}\left(a_{1}, \ldots, a_{n_{i n t}}\right)=a_{1} \ldots a_{n_{i n t}} \mathcal{K}_{i n t}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right) .
$$

## Laplacian of a graph

## Definition

Let $G$ be a graph with $n$ edges and $r$ vertices. To each edge $e_{j}$ one associates a parameter $a_{j}$. The Laplacian of the graph $G$ is a $r \times r$-matrix $L$, whose entries are given by
$L_{i j}= \begin{cases}\sum a_{k} & \text { if } i=j \text { and edge } e_{k} \text { is attached to } v_{i} \text { and is not a self-loop, } \\ -\sum a_{k} & \text { if } i \neq j \text { and edge } e_{k} \text { connects } v_{i} \text { and } v_{j} .\end{cases}$

## Laplacian with respect to internal vertices and edges

In Feynman graphs one distinguishes between external and internal edges. This motivates the following definition.

## Definition

Denote by $G_{i n t}$ the internal graph of $G$. The Laplacian of $G$ w.r.t. internal vertices and edges is defined as

$$
L_{i n t}(G)=L\left(G_{i n t}\right)
$$

## Example


$\left(a_{1}+a_{4}\right.$

## Example


$\left(\begin{array}{cc}a_{1}+a_{4} & \\ & a_{1}+a_{2}+a_{5}\end{array}\right.$

## Example



$$
\left(\begin{array}{lll}
a_{1}+a_{4} & \\
& a_{1}+a_{2}+a_{5} & \\
& & a_{3}+a_{5}
\end{array}\right.
$$

## Example



$$
\left(\begin{array}{cccc}
a_{1}+a_{4} & & \\
& a_{1}+a_{2}+a_{5} & & \\
& & a_{3}+a_{5} & \\
& & & a_{2}+a_{3}+a_{4}
\end{array}\right)
$$

## Example



$$
\left(\begin{array}{cccc}
a_{1}+a_{4} & -a_{1} & & \\
-a_{1} & a_{1}+a_{2}+a_{5} & & \\
& & a_{3}+a_{5} & \\
& & & a_{2}+a_{3}+a_{4}
\end{array}\right)
$$

## Example



$$
\left(\begin{array}{cccc}
a_{1}+a_{4} & -a_{1} & 0 & -a_{4} \\
-a_{1} & a_{1}+a_{2}+a_{5} & -a_{5} & -a_{2} \\
0 & -a_{5} & a_{3}+a_{5} & -a_{3} \\
-a_{4} & -a_{2} & -a_{3} & a_{2}+a_{3}+a_{4}
\end{array}\right)
$$

## Matrix-tree theorem

We write $L[i]$ for the submatrix of $L$ obtained by deleting the $i$ th row and column.

## Matrix-tree theorem

We write $L[i]$ for the submatrix of $L$ obtained by deleting the $i$ th row and column.

Theorem
$\mathcal{K}=\operatorname{det} L[i]$.

## Matrix-tree theorem

We write $L[i]$ for the submatrix of $L$ obtained by deleting the $i$ th row and column.

Theorem
$\mathcal{K}=\operatorname{det} L[i]$.
In particular, for every internal vertex $v_{i}$ one has $\mathcal{K}_{\text {int }}=\operatorname{det} L_{i n t}[i]$. One can then recover the first Symanzik polynomial $\mathcal{U}$ from $\mathcal{K}_{\text {int }}$ using

$$
\mathcal{U}\left(a_{1}, \ldots, a_{n_{\text {int }}}\right)=a_{1} \ldots a_{n_{\text {int }}} \mathcal{K}_{i n t}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{i n t}}}\right) .
$$

## Why matrix-tree?

The number of monomials in the Kirchhoff polynomial $\mathcal{K}$ of $G$ is equal to the number of spanning trees of $G$. Thus, evaluating the Kirchhoff polynomial at the vector $(1, \ldots, 1)$ counts this number. The matrix-tree theorem relates this to determinants of minors of the Laplacian.

## Moving on to the second Symanzik polynomial

To obtain an expression for the second Symanzik polynomial, one needs to generalize the matrix tree theorem.

## Moving on to the second Symanzik polynomial

To obtain an expression for the second Symanzik polynomial, one needs to generalize the matrix tree theorem. As before, we consider a graph with $r$ vertices. Let $I=\left(i_{1}, \ldots, i_{k}\right)$ with $1 \leqslant i_{1}<\ldots<i_{k} \leqslant r$ and $J=\left(j_{1}, \ldots, j_{k}\right)$ with $1 \leqslant j_{1}<\ldots<j_{k} \leqslant r$. We write $|I|=i_{1}+\ldots+i_{k}$ and $|J|=j_{1}+\ldots+j_{k}$.

## Moving on to the second Symanzik polynomial

To obtain an expression for the second Symanzik polynomial, one needs to generalize the matrix tree theorem. As before, we consider a graph with $r$ vertices. Let $I=\left(i_{1}, \ldots, i_{k}\right)$ with $1 \leqslant i_{1}<\ldots<i_{k} \leqslant r$ and $J=\left(j_{1}, \ldots, j_{k}\right)$ with $1 \leqslant j_{1}<\ldots<j_{k} \leqslant r$. We write $|I|=i_{1}+\ldots+i_{k}$ and $|J|=j_{1}+\ldots+j_{k}$. Let $L[I, J]$ denote the submatrix of $L$ obtained by deleting the rows from $I$ and columns from $J$.

## Moving on to the second Symanzik polynomial

We denote by $\mathcal{T}_{k}^{l, J}$ the set of all spanning $k$-forests such that each tree in a forest contains exactly one vertex $v_{i_{\alpha}}$ and one vertex $v_{j_{\beta}}$.

## Moving on to the second Symanzik polynomial

We denote by $\mathcal{T}_{k}^{l, J}$ the set of all spanning $k$-forests such that each tree in a forest contains exactly one vertex $v_{i_{\alpha}}$ and one vertex $v_{j_{\beta}}$. We can write an element $F \in \mathcal{T}_{k}^{I, J}$ as $F=\left(T_{1}, \ldots, T_{k}\right)$, where $T_{i}$ 's are trees.

## Moving on to the second Symanzik polynomial

We denote by $\mathcal{T}_{k}^{l, J}$ the set of all spanning $k$-forests such that each tree in a forest contains exactly one vertex $v_{i_{\alpha}}$ and one vertex $v_{j_{\beta}}$. We can write an element $F \in \mathcal{T}_{k}^{l, J}$ as $F=\left(T_{1}, \ldots, T_{k}\right)$, where $T_{i}$ 's are trees. We can enumerate the $T_{i}$ 's so that $v_{i_{\alpha}} \in T_{\alpha}$.

## Moving on to the second Symanzik polynomial

We denote by $\mathcal{T}_{k}^{l, J}$ the set of all spanning $k$-forests such that each tree in a forest contains exactly one vertex $v_{i_{\alpha}}$ and one vertex $v_{j_{\beta}}$. We can write an element $F \in \mathcal{T}_{k}^{l, J}$ as $F=\left(T_{1}, \ldots, T_{k}\right)$, where $T_{i}$ 's are trees. We can enumerate the $T_{i}$ 's so that $v_{i_{\alpha}} \in T_{\alpha}$. Each tree in $F$ contains exactly one $v_{j_{\alpha}}$, thus, there exists a permutation $\pi_{F} \in S_{k}$ such that $v_{j_{\alpha}} \in T_{\pi_{F}(\alpha)}$.

## All-minors matrix-tree theorem

Theorem
$\operatorname{det} L[I, J]=(-1)^{|/|+|J|} \sum_{F \in \mathcal{T}_{k}^{I, J}} \operatorname{sign}\left(\pi_{F}\right) \prod_{e_{j} \in F} a_{j}$.

The all-minors matrix-tree theorem provides a way to recover the second Symanzik polynomial $\mathcal{F}$.

The all-minors matrix-tree theorem provides a way to recover the second Symanzik polynomial $\mathcal{F}$.
Consider a graph $G$ with $n_{i n t}$ internal edges $\left(e_{1}, \ldots, e_{n_{\text {int }}}\right)$, $r_{\text {int }}$ internal vertices $\left(v_{1}, \ldots, v_{r_{\text {int }}}\right), n_{\text {ext }}$ external edges $\left(e_{n_{\text {int }}+1}, \ldots, e_{n_{\text {int }}+n_{\text {ext }}}\right)$ and $n_{\text {ext }}$ external vertices $\left(v_{r_{\text {int }}+1}, \ldots, v_{\text {rint }}+n_{\text {ext }}\right)$.

The all-minors matrix-tree theorem provides a way to recover the second Symanzik polynomial $\mathcal{F}$.
Consider a graph $G$ with $n_{\text {int }}$ internal edges $\left(e_{1}, \ldots, e_{n_{\text {int }}}\right), r_{\text {int }}$ internal vertices $\left(v_{1}, \ldots, v_{r_{\text {int }}}\right), n_{\text {ext }}$ external edges $\left(e_{n_{\text {int }}+1}, \ldots, e_{n_{\text {int }}+n_{\text {ext }}}\right)$ and $n_{\text {ext }}$ external vertices $\left(v_{r_{\text {int }}+1}, \ldots, v_{r_{\text {int }}+n_{\text {ext }}}\right)$. We associate the parameters $a_{i}$ to the internal edges $e_{i}\left(1 \leqslant i \leqslant n_{i n t}\right)$ and parameters $b_{j}$ to the external edges $e_{n_{\text {int }}+j}\left(1 \leqslant j \leqslant n_{\text {ext }}\right)$.

Now consider the polynomial

$$
\mathcal{W}\left(a_{1}, \ldots, a_{n_{\text {int }}}, b_{1}, \ldots, b_{n_{\text {ext }}}\right)=\operatorname{det} L(G)\left[r_{\text {int }}+1, \ldots, r_{\text {int }}+n_{\text {ext }}\right] .
$$

$\mathcal{W}$ is a polynomial of degree $r_{\text {int }}=n_{\text {int }}-I+1$.

Now consider the polynomial

$$
\mathcal{W}\left(a_{1}, \ldots, a_{n_{\text {int }}}, b_{1}, \ldots, b_{n_{\text {ext }}}\right)=\operatorname{det} L(G)\left[r_{\text {int }}+1, \ldots, r_{\text {int }}+n_{\text {ext }}\right]
$$

$\mathcal{W}$ is a polynomial of degree $r_{\text {int }}=n_{\text {int }}-I+1$.
We write $\mathcal{W}$ as a sum of polynomials homogeneous in the variables $b_{j}$ : $\mathcal{W}=\mathcal{W}^{(0)}+\ldots+\mathcal{W}^{(m)}$, where $\mathcal{W}^{(k)}$ is homogeneous of degree $k$ in the variables $b_{j}$.

Now consider the polynomial

$$
\mathcal{W}\left(a_{1}, \ldots, a_{n_{\text {int }}}, b_{1}, \ldots, b_{n_{\text {ext }}}\right)=\operatorname{det} L(G)\left[r_{\text {int }}+1, \ldots, r_{\text {int }}+n_{\text {ext }}\right]
$$

$\mathcal{W}$ is a polynomial of degree $r_{\text {int }}=n_{\text {int }}-I+1$.
We write $\mathcal{W}$ as a sum of polynomials homogeneous in the variables $b_{j}$ : $\mathcal{W}=\mathcal{W}^{(0)}+\ldots+\mathcal{W}^{(m)}$, where $\mathcal{W}^{(k)}$ is homogeneous of degree $k$ in the variables $b_{j}$.
Furthermore, we write

$$
\mathcal{W}^{(k)}=\sum_{\left(j_{1}, \ldots, j_{k}\right)} \mathcal{W}_{\left(j_{1}, \ldots, j_{k}\right)}^{(k)}\left(a_{1}, \ldots, a_{n_{i n t}}\right) b_{j_{1}} \ldots b_{j_{k}}
$$

where the sum is over all indices with $1 \leqslant j_{1}<\ldots<j_{k} \leqslant n_{\text {ext }}$.

The $\mathcal{W}_{\left(j_{1}, \ldots, j_{k}\right)}^{(k)}$ are homogeneous polynomials of degree $r_{i n t}-k$ in the variables $a_{i}$. One finds that

$$
\mathcal{W}^{(0)}=0, \mathcal{W}^{(1)}=\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{\text {int }}}\right) \sum_{j=1}^{n_{\text {ext }}} b_{j}
$$

The $\mathcal{W}_{\left(j_{1}, \ldots, j_{k}\right)}^{(k)}$ are homogeneous polynomials of degree $r_{\text {int }}-k$ in the variables $a_{i}$. One finds that

$$
\mathcal{W}^{(0)}=0, \mathcal{W}^{(1)}=\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{\text {int }}}\right) \sum_{j=1}^{n_{\text {ext }}} b_{j}
$$

Therefore,

$$
\mathcal{U}=a_{1} \ldots a_{n_{i n t}} \mathcal{W}_{(j)}^{(1)}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right)
$$

for any $j$.

The $\mathcal{W}_{\left(j_{1}, \ldots, j_{k}\right)}^{(k)}$ are homogeneous polynomials of degree $r_{\text {int }}-k$ in the variables $a_{i}$. One finds that

$$
\mathcal{W}^{(0)}=0, \mathcal{W}^{(1)}=\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{\text {int }}}\right) \sum_{j=1}^{n_{\text {ext }}} b_{j}
$$

Therefore,

$$
\mathcal{U}=a_{1} \ldots a_{n_{i n t}} \mathcal{W}_{(j)}^{(1)}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right)
$$

for any $j$.
For $\mathcal{F}_{0}$ one has

$$
\mathcal{F}_{0}=a_{1} \ldots a_{n_{i n t}} \sum_{(j, k)}\left(\frac{p_{j} \cdot p_{k}}{\mu^{2}}\right) \cdot \mathcal{W}_{(j, k)}^{(2)}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right)
$$

The $\mathcal{W}_{\left(j_{1}, \ldots, j_{k}\right)}^{(k)}$ are homogeneous polynomials of degree $r_{\text {int }}-k$ in the variables $a_{i}$. One finds that

$$
\mathcal{W}^{(0)}=0, \mathcal{W}^{(1)}=\mathcal{K}_{i n t}\left(a_{1}, \ldots, a_{n_{\text {int }}}\right) \sum_{j=1}^{n_{\text {ext }}} b_{j}
$$

Therefore,

$$
\mathcal{U}=a_{1} \ldots a_{n_{i n t}} \mathcal{W}_{(j)}^{(1)}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right)
$$

for any $j$.
For $\mathcal{F}_{0}$ one has

$$
\mathcal{F}_{0}=a_{1} \ldots a_{n_{i n t}} \sum_{(j, k)}\left(\frac{p_{j} \cdot p_{k}}{\mu^{2}}\right) \cdot \mathcal{W}_{(j, k)}^{(2)}\left(\frac{1}{a_{1}}, \ldots, \frac{1}{a_{n_{\text {int }}}}\right)
$$

Then $\mathcal{F}$ is obtained by

$$
\mathcal{F}(a)=\mathcal{F}_{0}(a)+\mathcal{U}(a) \sum_{i=1}^{n_{\text {int }}} a_{i} \frac{m_{i}^{2}}{\mu^{2}}
$$

## Deletion and contraction of edges

An edge of a graph is called a bridge if deleting this edge increases the number of connected components.

## Deletion and contraction of edges

An edge of a graph is called a bridge if deleting this edge increases the number of connected components. If an edge is neither a bridge nor a self-loop, then it is called a regular edge.

## Deletion and contraction of edges

An edge of a graph is called a bridge if deleting this edge increases the number of connected components. If an edge is neither a bridge nor a self-loop, then it is called a regular edge. For a graph $G$ and a regular edge $e$ we define $G / e$ to be the graph obtained from $G$ by contracting $e$ and $G-e$ to be the graph obtained from $G$ by deleting $e$.

## Deletion and contraction of edges

An edge of a graph is called a bridge if deleting this edge increases the number of connected components. If an edge is neither a bridge nor a self-loop, then it is called a regular edge. For a graph $G$ and a regular edge $e$ we define $G / e$ to be the graph obtained from $G$ by contracting $e$ and $G-e$ to be the graph obtained from $G$ by deleting $e$.
The Laplacian of the graph behaves nicely under these operations. This allows to define graph polynomials $\mathcal{U}$ and $\mathcal{F}$ recursively.

## Deletion and contraction of edges

An edge of a graph is called a bridge if deleting this edge increases the number of connected components. If an edge is neither a bridge nor a self-loop, then it is called a regular edge. For a graph $G$ and a regular edge $e$ we define $G / e$ to be the graph obtained from $G$ by contracting $e$ and $G-e$ to be the graph obtained from $G$ by deleting $e$.
The Laplacian of the graph behaves nicely under these operations. This allows to define graph polynomials $\mathcal{U}$ and $\mathcal{F}$ recursively. For any regular egde $e_{k}$ we have

$$
\begin{aligned}
\mathcal{U}(G) & =\mathcal{U}\left(G / e_{k}\right)+a_{k} \mathcal{U}\left(G-e_{k}\right) \\
\mathcal{F}_{0}(G) & =\mathcal{F}_{0}\left(G / e_{k}\right)+a_{k} \mathcal{F}_{0}\left(G-e_{k}\right)
\end{aligned}
$$

## Deletion and contraction of edges

The recursion terminates when all edges are either bridges or self-loops. Graphs with such property are called terminal forms.

## Deletion and contraction of edges

The recursion terminates when all edges are either bridges or self-loops. Graphs with such property are called terminal forms. For such graphs we have

$$
\mathcal{U}=a_{r_{\text {int }}} \ldots a_{n_{\text {int }}}, \mathcal{F}_{0}=a_{r_{\text {int }}} \ldots a_{n_{\text {int }}} \sum_{j=1}^{r_{\text {int }}-1} a_{j}\left(\frac{-q_{j}^{2}}{\mu^{2}}\right)
$$

where the parameters $a_{r_{\text {int }}}, \ldots, a_{n_{\text {int }}}$ correspond to independent loop momenta.

